

CLAIMS

What is claimed is:

1           1. A processing machine comprising:

2           (a)    a data memory;

3           (b)    a control engine, linked in communication with the data  
4   memory;

5           (c)    an instruction memory in which instructions may be stored,  
6   having an input for receiving control information from the control engine;

7           (d)    a plurality of coprocessors, each connected in  
8   communication with the data memory and the control engine,

9           each of said control engine and plurality of coprocessors being  
10   enabled to performance simultaneous functions in response to a single  
11   instruction.

1           2. The processing machine of claim 1, wherein the control engine  
2   comprises a microcontroller.

1           3. The processing machine of claim 1, further comprising a main  
2   memory linked in communication with at least one of said plurality of  
3   coprocessors.

1           4. The processing machine of claim 3, wherein said at least one  
2 coprocessor comprises a bus interface coprocessor.

1           5. The processing machine of claim 1, wherein the processing  
2 machine is used to perform a particular task and wherein each  
3 coprocessor is designated to perform at least one specific subtask of that  
4 particular task.

1           6. The processing machine of claim 5, wherein the particular task  
2 comprises processing a data manipulation algorithm, and specific  
3 subtasks performed by separate coprocessors include a memory bus  
4 interface function and a data processing algorithm function.

1           7. The processing machine of claim 6, wherein the data  
2 processing algorithm comprises an encryption algorithm.

1           8. A processing machine comprising:

2           (a) a data memory;

3           (b) a main memory;

4           (c) a microcontroller, linked in communication with the data  
5 memory;

6           (d) an instruction memory in which instructions may be stored,  
7 having an input for receiving control information from the microcontroller;

8           (e)     a first coprocessor providing a bus interface function when  
9     operational, linked in communication with each of the main memory, the  
10    data memory, and the microcontroller, and having an input to receive  
11    instructions from the instruction memory; and  
12           (f)     a second coprocessor, linked in communication with the  
13    data memory and the microcontroller and having an input to receive  
14    instructions from the instruction memory.

1           9. The processing machine of claim 8, further comprising:  
2           a third coprocessor, linked in communication with the data memory  
3    and the microcontroller and having an input to receive instructions from  
4    the instruction memory.

1           10. The processing machine of claim 9, further comprising:  
2           a fourth coprocessor, linked in communication with the data  
3    memory and the microcontroller and having an input to receive  
4    instructions from the instruction memory.

1           11. The processing machine of claim 8, wherein each of the first  
2    and second processors and the microcontroller perform simultaneous  
3    coordinated functions in response to a single instruction issued from the  
4    instruction memory.

1           12. The processing machine of claim 8, wherein the second  
2 coprocessor is enabled to process a data manipulation algorithm.

1           13. The processing machine of claim 9, wherein the third  
2 processor is enabled to perform an ATM data transfer interface function.

1           14. The processing machine of claim 10, wherein the third  
2 processor is enabled to perform an ATM data transfer interface function  
3 when operational and the fourth processor is enabled to perform an ATM  
4 Adaptation Layer (AAL) function when operational.

1           15. A method of processing a data manipulation task with a  
2 processing machine including a control engine and a plurality of  
3 coprocessors, comprising;  
4           dividing the data manipulation task into a plurality of subtasks;  
5           issuing a sequence of instructions having a plurality of portions to  
6 the control engine and each of said plurality of coprocessors;  
7           performing separate subtasks with the control engine and each of  
8 said plurality of coprocessors in response to corresponding portions of the  
9 instructions received by each of these components; and  
10          coordinating an execution of each portion of instructions received  
11 by the control engine and each of said plurality of coprocessors such that

12 the subtasks performed by these components are performed substantially  
13 in parallel.

1 16. The method of claim 15, wherein the coordination of the  
2 execution of the portions of instructions is performed by the control engine  
3 via execution control signals sent to each of said plurality of coprocessors.

1 17. The method of claim 16, wherein the processing machine  
2 comprises a programmed state machine and wherein each of the control  
3 engine and said plurality of coprocessors is caused to cycle through a  
4 respective set of machine states in response to instruction portions  
5 received by that component.

1 18. The method of claim 15, wherein one of the subtasks  
2 comprises a bus interface function.

1 19. The method of claim 15, wherein the control engine comprises  
2 a microcontroller.

1 20. The method of claim 15, wherein each instruction is issued  
2 from an instruction memory in response to an address sent to the  
3 instruction memory from the control engine.